

Optimal Public Debt with Life Cycle Motives*

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Abstract

In a seminal paper, Aiyagari and McGrattan (1998) find that in a standard incomplete markets model with infinitely lived agents it is optimal for the U.S. government to hold a large amount of public debt. Debt is optimal because it induces a higher interest rate, which encourages more household savings and better self-insurance. This paper revisits their result in a life cycle model only to find that public debt's insurance enhancing mechanism is severely limited. While a higher interest rate encourages higher average savings in both models, the benefits vary. In a life cycle model, agents enter the economy with no savings but must accumulate the higher level of savings throughout their lifetime, thereby eliminating some of the benefits. In contrast, infinitely lived agents do not accumulate savings over a lifetime and, thus, simply enjoy the benefit of the higher average savings *ex ante*. Overall, we find that while optimal debt is equal to 22% of output in the infinitely lived agent model, when a life cycle is introduced it is optimal for the government to hold savings equal to 59% of output. Not accounting for life cycle features when computing optimal policy reduces welfare by nearly one-half percent of expected lifetime consumption.

Keywords: Government Debt; Life Cycle; Heterogeneous Agents; Incomplete Markets

JEL Codes: H6, E21, E6

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1 Introduction

In the decades preceding the Great Recession, debt to GDP ratios in advanced economies averaged over 40 percent. Moreover, only three advanced economies held a net level of public savings. Motivated by these basic facts, this paper examines the optimality of public debt in the U.S. economy.

In their seminal work, [Aiyagari and McGrattan \(1998\)](#) find that it is optimal for the government to hold a large amount of public debt, on the order of magnitude of two-thirds the size of GDP. Their framework is the standard incomplete markets model, in which infinitely lived households can only partially insure against the realization of idiosyncratic labor productivity shocks. Using this model, [Aiyagari and McGrattan \(1998\)](#) show that imperfect insurance against ex post labor market outcomes admits a role for government policy to improve upon the competitive equilibrium allocation. Higher government debt (or lower government savings) tends to crowd out the stock of productive capital leading to a higher interest rate and lower wage. The relatively higher interest rate encourages households to hold more wealth, which in turn helps agents to better insure against labor earnings risk and avoid binding liquidity constraints.

This paper examines whether public debt remains optimal in a life cycle model. Given that introducing a life cycle can fundamentally alter households' savings patterns, a life cycle may change both the effectiveness and benefit of public debt in encouraging households to hold more wealth, thereby changing optimal policy. In order to determine the effect of the life cycle, we compute optimal policy in two model economies that are calibrated to be consistent with post-war U.S. macroeconomic aggregates and microdata. The first model is similar to that in [Aiyagari and McGrattan \(1998\)](#) and includes infinitely lived agents. The second model includes life cycle features such as a finite lifespan, mortality risk, an age-dependent wage profile, retirement and a Social Security program. We find that the optimal policies are strikingly different in the two models. In the infinitely lived agent model it is optimal for the government to hold debt equal to 22 percent of output. In contrast, in the life cycle model, we find that it is no longer optimal for the government to hold debt. Instead, it is optimal for the government to hold public savings

equal to 59 percent of output.

Not only does the optimal policy look quite different when one ignores life cycle features, but the welfare consequences of ignoring them are economically significant. In the life cycle model, we find that if a government implemented the 22 percent debt-to-output policy that is optimal in the infinitely lived agent model, then life cycle agents would be worse off by nearly 0.5 percent of expected lifetime consumption. Overall, this paper demonstrates that incorporating life cycle features fundamentally changes whether it is optimal for the government to hold public savings or public debt.

The starkly different optimal policies can be explained, in large part, by life cycle agents' special progression through distinct phases over their life times. Specifically, life cycle model agents begin their life with no savings and enter an *accumulation phase* in which they accumulate a precautionary stock of savings to insure against income shocks and finance their post-retirement consumption. In middle life, agents may enter a *stationary phase* in which they have accumulated a target level of assets, around which savings fluctuates.¹ Finally, older agents enter a *deaccumulation phase* in which they spend down their savings in anticipation of death. In the infinitely lived agent model, agents do not experience an accumulation phase but instead experience a perpetual stationary phase.

Using the life cycle model, we demonstrate that agents' progression through distinct lifetime phases is the underlying mechanism leading to a different optimal policy. In particular, the benefit from public debt that induces more household savings may vary between the two models. In the infinitely lived agent model the steady state level of aggregate savings is higher and thus the average agent has more ex ante wealth. In contrast, in the life cycle model, agents enter the economy with no savings but must accumulate the higher level of savings throughout their lifetime, thereby eliminating some of the benefits. Therefore, the existence of the accumulation phase is the predominant reason for the drastically different optimal policies between the two models.

¹In life cycle models where agents live for a short enough span, agents sometimes transition directly from the accumulation phase to the deaccumulation phase skipping this stationary phase. We generally find this to be the case in our baseline life cycle model.

This paper is related to an established literature that uses the standard incomplete market model with infinitely lived agents, originally developed in [Bewley \(1986\)](#), [İmrohoroglu \(1989\)](#), [Huggett \(1993\)](#) and [Aiyagari \(1994\)](#), to study the optimal level of steady state government debt. In contrast to this paper, previous work has almost exclusively studied infinitely lived agent models and tends to find that public debt is optimal. [Aiyagari and McGrattan \(1998\)](#) is the seminal contribution to the study of optimal debt in the standard incomplete market model, on which this paper and others build. [Floden \(2001\)](#) finds that increasing government debt can provide welfare benefits if transfers are below optimal levels. Similarly, [Dyrda and Pedroni \(2016\)](#) find that it is optimal for the government to hold debt. However they find that when optimizing both taxes and debt at the same time leads to a smaller level of optimal debt than previous studies. A notable exception is [Röhrs and Winter \(2016\)](#), who find that when making a number of changes to [Aiyagari and McGrattan's \(1998\)](#) model, such as introducing a skewed wealth distribution that more closely matches the upper tail of the U.S. wealth distribution, it is optimal for the government to save as opposed to hold debt. Relative to these papers, we study optimal public debt and savings in a life cycle model as opposed to an infinitely lived agent model, and find that including life cycle features has large effects on optimal policy.²

This paper is also related to a literature that studies optimal capital taxation. Seminal contributions of [Judd \(1985\)](#) and [Chamley \(1986\)](#) prove the optimality of zero capital taxation in the long-run of a representative agent growth model with complete markets. Later contributions in [Aiyagari \(1995\)](#) and [İmrohoroglu \(1998\)](#) studied an incomplete markets models and found that a long-run optimal capital tax is positive in the presence of uninsurable earnings shocks when borrowing constraints are sufficiently tight. Most pertinent to the present paper is the literature on optimal capital taxation in heterogeneous agent, life cycle economies with incomplete markets. In several variants of this model, [Garriga \(2001\)](#), [Erosa and Gervais \(2002\)](#) and [Conesa](#)

²Using infinitely lived agent models, [Desbonnet and Weitzblum \(2012\)](#), [Açıkgöz \(2015\)](#), [Dyrda and Pedroni \(2016\)](#), [Röhrs and Winter \(2016\)](#) find quantitatively large welfare costs of transitioning between steady states after a change in public debt. We do not consider these transitional costs and instead focus on steady state comparisons to more sharply highlight the effect of the life cycle on optimal debt policy.

[et al. \(2009\)](#) show that introducing a life cycle creates an additional motive for positive capital taxation. In particular, a capital tax can distort savings in a way that effectively mimics an optimal age-varying policy. While this paper aligns itself most closely with these latter papers using life cycle models, we focus on optimal debt policy instead of capital taxation. Moreover, we find that in the life cycle model it is optimal for the government to hold savings as opposed to debt, not to create age-variation in policy but because the accumulation phase mitigates the welfare benefits from a higher interest rate.

Finally, our paper is related to [Dávila, Hong, Krusell, and Ríos-Rull \(2012\)](#), whose work defines constrained efficiency in a standard incomplete markets model with infinitely lived agents. Constrained efficient allocations must satisfy individuals' constraints but account for the effect of individual behavior on market clearing prices. The authors show that if individual agents, who are constrained by incomplete asset markets and borrowing constraints, were to systematically deviate from individually optimal savings, consumption and hours decisions, then equilibrium prices could be attained that improve social welfare. Therefore, the price system in the standard incomplete market model does not efficiently allocate resources and competitive equilibria are generically constrained inefficient. While this paper does not characterize constrained efficient allocations, it focuses on the problem of a Ramsey planner (or government) that, because it understands the relationship between public debt and factor prices, can implement a welfare improving allocation that individual agents could not attain alone. Even though our paper restricts the set of allocations that the planner can implement, both papers arrive at a similar conclusion that under certain assumptions the current U.S. capital stock is too low. [Dávila, Hong, Krusell, and Ríos-Rull \(2012\)](#) demonstrate that more productive capital is constrained optimal after changing the idiosyncratic labor productivity process to induce more wealth inequality. In comparison, this paper demonstrates that the optimal debt policy induces an equilibrium with more productive capital when a life cycle is introduced.

The remainder of this paper is organized as follows. [Section 2](#) illustrates the underlying mechanisms by which optimal government policy interacts with life cycle and infinitely lived agent model features. [Section 3](#) describes the life cycle and infinitely lived agent model environments and defines equi-

librium. [Section 4](#) presents the calibration strategy and [Section 5](#) presents quantitative results. [Section 6](#) concludes.

2 Illustration of the Mechanisms

In this section, we illustrate the mechanisms that lead the government to an optimal public debt or savings policy. We discuss why optimal government policy may differ in the life cycle and infinitely lived agent models. Specifically, we highlight the distinct savings patterns induced by life cycle features relative to the infinitely lived agent model. Finally, we discuss the main channels by which public debt or savings impacts individual behavior and how the strength of these channels may vary between the two models.

2.1 Life Cycle Phases

In order to highlight how the life cycle may impact optimal debt policy, it will be useful to consider the following illustrative example. Suppose that agents are born with zero wealth, work throughout their lifetimes and die with certainty within a finite number of periods. Agents face idiosyncratic labor productivity shocks and use assets to partially insure against the resulting earnings risk.

For this hypothetical economy, [Figure 1](#) depicts cross-sectional averages for savings, hours and consumption decisions at each age. [Figure 1](#) shows that agents experience three different phases. Agents enter the economy without any wealth and begin the *accumulation phase*, which is characterized by the accumulation of wealth for precautionary motives.³ While accumulating a stock of savings, agents tend to work more and consume less.

Once a cohort's average wealth provides sufficient insurance against labor productivity shocks, these agents have entered the *stationary phase*.⁴ This

³Since agents do not retire from supplying labor in this simplified economy, wealth accumulation only provides self-insurance and does not finance post-retirement consumption.

⁴The stationary level of average savings is related to the "target savings level" in [Carroll \(1992, 1997\)](#). Given the primitives of the economy, an agent faces a tradeoff between consumption levels and consumption smoothing. The agent targets a level of savings that provides sufficient insurance while maximizing expected consumption.

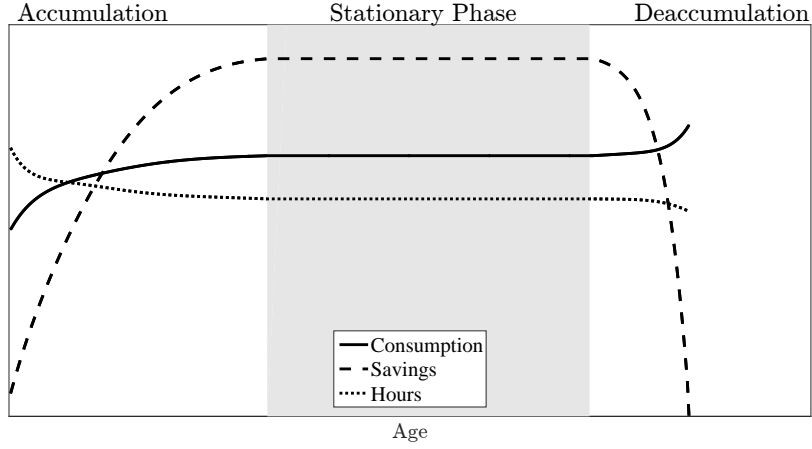


Figure 1: Illustrative example of life cycle phases. This graph depicts the cross-sectional averages of consumption, savings and hours during the accumulation, stationary and deaccumulation phases.

phase is characterized by savings, hours and consumption that remain constant in the aggregate. However, underlying constant aggregates are agents who respond to shocks by choosing different allocations, thereby moving about various states within a non-degenerate distribution over savings, hours and consumption.

Finally, agents enter the *deaccumulation phase* as they approach the end of their lives. In order to smooth consumption in the final periods of their lives, agents attempt to deaccumulate assets so that they are not forced to consume a large quantity immediately preceding death. Furthermore, with few periods of life remaining, agents no longer want to hold as much savings for precautionary reasons. Thus, the average level of savings and labor supply decreases, while consumption increases slightly.

2.2 Welfare Channels and Life Cycle Features

We identify three main channels through which public debt policy affects welfare: the *direct effect*, the *insurance channel*, and the *inequality channel*. We heuristically characterize how these channels differ across life cycle and infinitely lived agent economies and lead to different optimal policies.

Direct Effect: The *direct effect* is the partial equilibrium change in the productive capital stock, aggregate consumption and aggregate output with respect to a change in public debt, when holding constant the aggregate labor supply and aggregate private savings. Mechanically, shifting from public debt toward public savings creates more productive capital, thereby generating more output and increasing aggregate consumption.⁵ Generally, increased aggregate consumption improves welfare. Furthermore, absent any general equilibrium effects, this mechanism should operate similarly in both the life cycle and infinitely lived agent economies.

While this partial equilibrium channel is a direct effect of policy on aggregate resources, the remaining two channels affect welfare through general equilibrium effects, that is, by changing the distribution of resources and impacting market clearing prices.

Insurance Channel: A government that holds more public debt mechanically crowds out productive capital and induces a higher interest rate in asset markets. The higher interest rate tends to accompany a higher level of average precautionary savings. All else equal, the higher level of precautionary savings can improve welfare because agents are less likely to face binding liquidity constraints and are, therefore, better insured against labor earnings risk. We refer to this channel as the *insurance channel*.

The insurance channel's benefit from public debt is fundamentally different in the life cycle and infinitely lived agent models. Generally, if the government holds more public debt, then the *steady state* level of aggregate savings is higher. Infinitely lived agents exist in a perpetual stationary phase and, as a result, higher steady state aggregate savings implies that the average agent has more *ex ante* wealth. In contrast, life cycle model agents enter the econ-

⁵While aggregate output increases with capital and labor inputs, in general equilibrium, aggregate consumption nor aggregate private savings need increase with aggregate output. It could be the case that an increase in public savings increases the productive capital stock while crowding out private savings. Furthermore, because we assume a constant returns to scale production technology that exhibits decreasing marginal returns to capital, aggregate consumption and aggregate private savings may decrease when the aggregate capital stock is sufficiently large. However, in both models, our quantitative results show that within the range of public savings that we study, (i) aggregate consumption is increasing in public savings and (ii) the elasticity of private savings with respect to a unit increase in public savings is less than one, so that public savings increases private savings.

omy with zero wealth and immediately begin the accumulation phase.⁶ If the government holds more public debt then, on average, agents may hold more savings over their lifetime. However, agents must accumulate this wealth over their lifetime, which mitigates the welfare benefit from the insurance channel relative to the infinitely lived agent model. Overall, the benefit from the insurance channel tends to be larger in the infinitely lived agent model because it lacks the mitigating effects of the accumulation phase.

Inequality Channel: When markets are incomplete and agents are risk averse, ex post income inequality generates greater uncertainty over utility flows and worsens ex ante welfare. Income inequality is composed of inequality in both asset and labor income. Since changing public debt has opposite effects on the wage and interest rate, debt policy can be used to reduce the spread in lifetime total income across agents. For example, if labor income contributes more to lifetime total income inequality then increasing public debt will lower the wage and tend to decrease overall lifetime income inequality.⁷ Similarly, lowering public debt decreases overall income inequality when asset income contributes more to lifetime total income inequality.

As demonstrated in [Dávila, Hong, Krusell, and Ríos-Rull \(2012\)](#), the relative contribution of labor income and asset income to lifetime total income inequality depends on agents' lifespan. As agents live longer, lifetime labor income inequality increases because there is a greater chance that agents receive a long string of either positive or negative labor productivity shocks. However, asset income inequality will also develop because agents reduce (increase) their wealth in response to a string of negative (positive) shocks. Generally, as agents' lifespan increases, asset income becomes a relatively larger contributor to overall income inequality. Thus, in this case, the government can reduce lifetime total income inequality by holding less public debt,

⁶If life cycle features were introduced in a dynastic model, instead of a life cycle model, where old agents bequeath wealth to agents entering the economy, then the accumulation phase may be more responsive to public policy. Consistent with [Fuster, Imrohoroglu, and Imrohoroglu \(2008\)](#), the optimal policy differences with the infinitely lived agent model could be smaller since agents would receive some initial wealth through bequests.

⁷The increase in public debt will also increase the interest rate and introduce more inequality from interest income. However, this effect tends to be dominated by the lower of labor income inequality.

which lowers the interest rate and reduces asset income inequality.

3 Economic Environment

In this section, we present both the Life Cycle model and the Infinitely Lived Agent model. Given that there are many common features across models, we will first focus on the Life Cycle model in detail before providing an overview of the Infinitely Lived Agent model.

3.1 Life Cycle Model

3.1.1 Production

Assume there exist a large number of firms that sell goods in perfectly competitive product markets, purchase inputs from perfectly competitive factor markets and each operate an identical constant returns to scale production technology, $Y = ZF(K, L)$. These assumptions on primitives admit a representative firm. The representative firm chooses capital (K) and labor (L) inputs in order to maximize profits, given an interest rate r , a wage rate w , a level of total factor productivity Z and capital depreciation rate $\delta \in (0, 1)$.

3.1.2 Consumers

Demographics: Let time be discrete and let each model period represent a year. Each period, the economy is inhabited by J overlapping generations of individuals. We index agents' model age by $j = 1, \dots, J$ where J is each agent's exogenous terminal age of life. Before age J all living agents face mortality risk. Conditional on living to age j , agents have a probability s_j of living to age $j + 1$, with a terminal age probability given by $s_J = 0$. Each period a new cohort is born and the size of each successive newly born cohort grows at a constant rate $g_n > 0$.

Agents who die before age J may hold savings since mortality is uncertain. These savings are treated as accidental bequests and are equally divided across each living agent in the form of a lump-sum transfer, denoted Tr .

Preferences: Agents rank lifetime paths of consumption and labor, denoted $\{c_j, h_j\}_{j=1}^J$, according to the following preferences:

$$\mathbb{E}_1 \sum_{j=1}^J \beta^{j-1} s_j \left[u(c_j) - v(h_j, \zeta'_j) \right]$$

where β is the time discount factor. Expectations are taken with respect to the stochastic processes governing labor productivity. Furthermore, $u(c)$ and $v(h)$ are instantaneous utility functions over consumption and labor hours, respectively, satisfying standard conditions. Lastly, ζ'_j is a retirement decision that is described immediately below.

Retirement: Agents choose their retirement age, which is denoted by J_{ret} . A retired agent may not sell labor hours and the decision is irreversible. Agents endogenously determine retirement age in the interval $j \in [J_{ret}, \bar{J}_{ret}]$ and are forced to retire after age \bar{J}_{ret} . Let $\zeta'_j \equiv \mathbb{1}(j < J_{ret})$ denote an indicator variable that equals one when an agent chooses to continue working and zero upon retirement.

Labor Earnings: Agents are endowed with one unit of time per period, which they split between leisure and market labor. During each period of working life, an agent's labor earnings are $w e_j h_j$, where w is the wage rate per efficiency unit of labor, e_j is the agent's idiosyncratic labor productivity drawn at age j and h_j is the time the agent chooses to work at age j .

Following [Kaplan \(2012\)](#), we assume that labor productivity shocks can be decomposed into four sources:

$$\log(e_j) = \kappa + \theta_j + v_j + \epsilon_j$$

where (i) $\kappa \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_\kappa^2)$ is an individual-specific fixed effect that is drawn at birth, (ii) $\{\theta_j\}_{j=1}^J$ is an age-specific fixed effect, (iii) v_j is a persistent shock that follows an autoregressive process given by $v_{j+1} = \rho v_j + \eta_{j+1}$ with $\eta \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_\eta^2)$ and $\eta_1 = 0$, and (iv) $\epsilon_j \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_\epsilon^2)$ is a per-period transitory shock.

For notational compactness, we denote the relevant state as a vector $\varepsilon_j = (\kappa, \theta_j, v_j, \epsilon_j)$ that contains each element necessary for computing contempo-

aneous labor earnings, $e_j \equiv e(\varepsilon_j)$, and forming expectations about future labor earnings. Denote the Markov process governing the process for ε by $\pi_j(\varepsilon_{j+1}|\varepsilon_j)$ for each $j = 1, \dots, \bar{J}_{ret}$ and for each $\varepsilon_j, \varepsilon_{j+1}$.

Insurance: Agents have access to a single asset, a non-contingent one-period bond denoted a_j with a market determined rate of return of r . Agents may take on a net debt position, in which case they are subject to a borrowing constraint that requires their debt position be bounded below by $\underline{a} \in \mathbb{R}$. Agents are endowed with zero initial wealth, such that $a_1 = 0$ for each agent.

3.1.3 Government Policy

The government (i) consumes an exogenous amount G , (ii) collects linear Social Security taxes τ_{ss} on all pre-tax labor income below an amount \bar{x} , (iii) distributes lump-sum Social Security payments b_{ss} to retired agents, (iv) distributes accidental bequests as lump-sum transfers Tr , and (v) collects income taxes from each individual.

Social Security: The model's Social Security system consists of taxes and payments. The social security payroll tax is given by τ_{ss} with a per-period cap denoted by \bar{x} . We assume that half of the social security contributions are paid by the employee and half by the employer. Therefore, the consumer pays a payroll tax given by: $(1/2) \tau_{ss} \min\{weh_j, \bar{x}\}$. Social security payments are computed using an averaged indexed monthly earnings (AIME) that summarizes an agents lifetime labor earnings. Following [Huggett and Parra \(2010\)](#) and [Kitao \(2014\)](#), the AIME is denoted by $\{x_j\}_{j=1}^J$ and is given by:

$$x_{j+1} = \left\{ \begin{array}{ll} \frac{1}{j} (\min\{wejh_j, \bar{x}\} + (j-1)x_j) & \text{for } j \leq 35 \\ \max \left\{ x_j, \frac{1}{j} (\min\{wejh_j, \bar{x}\} + (j-1)x_j) \right\} & \text{for } j \in (35, J_{ret}) \\ x_j & \text{for } j \geq J_{ret} \end{array} \right\}$$

The AIME is a state variable for determining future benefits. Benefits consists of a base payment and an adjusted final payment. The base payment, denoted by $b_{base}^{ss}(x_{J_{ret}})$, is computed as a piecewise-linear function over the individual's

average labor earnings at retirement $x_{J_{ret}}$:

$$b_{base}^{ss}(x_{J_{ret}}) = \begin{cases} \tau_{r1} & \text{for } x_{J_{ret}} \in [0, b_1^{ss}) \\ \tau_{r2} & \text{for } x_{J_{ret}} \in [b_1^{ss}, b_2^{ss}) \\ \tau_{r3} & \text{for } x_{J_{ret}} \in [b_2^{ss}, b_3^{ss}) \end{cases}$$

Lastly, the final payment requires an adjustment that penalizes early retirement and credits delayed retirement. The adjustment is given by:

$$b_{ss}(x_{J_{ret}}) = \begin{cases} (1 - D_1(J_{nra} - J_{ret}))b_{base}^{ss}(x_{J_{ret}}) & \text{for } \underline{J}_{ret} \leq J_{ret} < J_{nra} \\ (1 + D_2(J_{ret} - J_{nra}))b_{base}^{ss}(x_{J_{ret}}) & \text{for } J_{nra} \leq J_{ret} \leq \bar{J}_{ret} \end{cases}$$

where $D_i(\cdot)$ are functions governing the benefits penalty or credit, \underline{J}_{ret} is the earliest age agents can retire, J_{nra} is the “normal retirement age” and \bar{J}_{ret} is the latest age an agent can retire.

Net Government Transfers: Taxable income is defined as labor income and capital income net of social security contributions from an employer:

$$y(h, a, \varepsilon, \zeta) \equiv \zeta we(\varepsilon)h + r(a + Tr) - \zeta \frac{\tau_{ss}}{2} \min\{we(\varepsilon)h, \bar{x}\}$$

The government taxes each individual’s taxable income according to an increasing and concave function, $Y(y(h, a, e, \zeta))$.

Define the function $T(\cdot)$ as the government’s net transfers of income taxes, social security payments and social security payroll taxes to working age agents (if $\zeta = 1$) and retired agents (if $\zeta = 0$). Net transfers are given by:

$$T(h, a, \varepsilon, x, \zeta) = (1 - \zeta)b_{ss}(x) - \zeta \frac{\tau_{ss}}{2} \min\{we(\varepsilon)h, \bar{x}\} - Y(y(h, a, \varepsilon, \zeta))$$

Public Savings and Budget Balance: Each period, the government accumulates savings, denoted B' , and collects asset income rB . The resulting govern-

ment budget constraint is:

$$G + B' - B = rB + Y_y \quad (1)$$

where Y_y is aggregate revenues from income taxation and G is an unproductive level of government expenditures.⁸ The model's Social Security system is self-financing and therefore does not appear in the governmental budget constraint.

3.1.4 Consumer's Problem

The agent's state variables consist of asset holdings a , labor productivity shocks $\varepsilon \equiv (\kappa, \theta, \nu, \epsilon)$, Social Security contribution (AIME) variable x and retirement status ζ . For age $j \in \{1, \dots, J\}$, the agent's recursive problem is:

$$\begin{aligned} V_j(a, \varepsilon, x, \zeta) = \max_{c, a', h, \zeta'} & \left[u(c) - v(h, \zeta') \right] + \beta s_j \sum_{\varepsilon'} \pi_j(\varepsilon' | \varepsilon) V_{j+1}(a', \varepsilon', x', \zeta') \quad (2) \\ \text{s.t.} \quad c + a' & \leq \zeta' we(\varepsilon)h + (1 + r)(a + Tr) + T(h, a, \varepsilon, x, \zeta') \\ a' & \geq \underline{a} \\ \zeta' & \in \{ \mathbb{1}(j < \underline{J}_{ret}), \mathbb{1}(j \leq \bar{J}_{ret}) \cdot \zeta \} \end{aligned}$$

The indicator function $\mathbb{1}(j < \underline{J}_{ret})$ equals one when an agent is too young to retire and equals zero thereafter. Additionally $\mathbb{1}(j \leq \bar{J}_{ret})$ equals zero for all ages after an agent must retire and equals one beforehand. Therefore the agent's recursive problem nests all three stages of life: working life, near-retirement and retirement.⁹

⁸Two recent papers, [Röhrs and Winter \(2016\)](#) and [Chatterjee, Gibson, and Rioja \(2016\)](#) have relaxed the standard Ramsey assumption that government expenditures are unproductive. Both papers show that public savings is optimal with productive government expenditures, intuitively because there is an additional benefit to aggregate output.

⁹During an agent's working life (ages $j < \underline{J}_{ret}$) the agent's choice set for retirement is $\zeta' \in \{1, 1\}$ and therefore the agent must continue working. Near retirement (ages $\underline{J}_{ret} \leq j \leq \bar{J}_{ret}$), the agent's choice set is $\zeta' \in \{0, 1\}$ and the agent may retire by choosing $\zeta' = 0$. Lastly, if an agent has retired either because he chose retirement at a previous date ($\zeta = 0$) or because of mandatory retirement ($j > \bar{J}_{ret}$), then the choice set is $\{0, 0\}$ and $\zeta' = \zeta = 0$.

3.1.5 Recursive Competitive Equilibrium

Agents are heterogeneous with respect to their age $j \in \mathbf{J} \equiv \{1, \dots, J\}$, wealth $a \in \mathbf{A}$, labor productivity $\varepsilon \in \mathbf{E}$, average lifetime earnings $x \in \mathbf{X}$ and retirement status $\zeta \in \mathbf{R} \equiv \{0, 1\}$. Let $\mathbf{S} \equiv \mathbf{A} \times \mathbf{E} \times \mathbf{X} \times \mathbf{R}$ be the state space and $\mathcal{B}(\mathbf{S})$ be the Borel σ -algebra on \mathbf{S} . Let \mathbf{M} be the set of probability measures on $(\mathbf{S}, \mathcal{B}(\mathbf{S}))$. Then $(\mathbf{S}, \mathcal{B}(\mathbf{S}), \lambda_j)$ is a probability space in which $\lambda_j(S) \in \mathbf{M}$ is a probability measure defined on subsets of the state space, $S \in \mathcal{B}(\mathbf{S})$, that describes the distribution of individual states across age- j agents. Denote the fraction of the population that is age $j \in \mathbf{J}$ by μ_j . For each set $S \in \mathcal{B}(\mathbf{S})$, $\mu_j \lambda_j(S)$ is the fraction of age $j \in \mathbf{J}$ and type $S \in \mathbf{S}$ agents in the economy. We can now define a recursive competitive equilibrium of the economy.

Definition (Equilibrium): Given a government policy $(G, B, B', Y, \tau_{ss}, b_{ss})$, a *stationary recursive competitive equilibrium* is (i) an allocation for consumers described by policy functions $\{c_j, a'_j, h_j, \zeta'_j\}_{j=1}^J$ and consumer value function $\{V_j\}_{j=1}^J$, (ii) an allocation for the representative firm (K, L) , (iii) prices (w, r) , (iv) accidental bequests Tr , and (v) distributions over agents' state vector at each age $\{\lambda_j\}_{j=1}^J$ that satisfy:

- (1) Given prices, policies and accidental bequests, $V_j(a, \varepsilon, x)$ solves the Bellman equation (2) with associated policy functions $c_j(a, \varepsilon, x, \zeta)$, $a'_j(a, \varepsilon, x, \zeta)$, $h_j(a, \varepsilon, x, \zeta)$ and $\zeta'_j(a, \varepsilon, x, \zeta)$.
- (2) Given prices (w, r) , the representative firm's allocation minimizes cost: $r = ZF_K(K, L) - \delta$ and $w = ZF_L(K, L)$
- (3) Accidental bequests, Tr , from agents who die at the end of this period are distributed equally across next period's living agents:

$$(1 + g_n)Tr = \sum_{j=1}^J (1 - s_j) \mu_j \int a'_j(a, \varepsilon, x, \zeta) d\lambda_j(a, \varepsilon, x, \zeta)$$

- (4) Government policies satisfy budget balance in equation (1), where aggre-

gate income tax revenue is given by:

$$Y_y \equiv \sum_{j=1}^J \mu_j \int Y \left(y(h_j(a, \varepsilon, x, \zeta), a, \varepsilon, \zeta'_j(a, \varepsilon, x, \zeta)) \right) d\lambda_j(a, \varepsilon, x, \zeta)$$

(5) Social security is self-financing:

$$\begin{aligned} & \sum_{j=1}^J \mu_j \int \zeta'_j(a, \varepsilon, x, \zeta) \tau_{ss} \min\{we(\varepsilon)h_j(a, \varepsilon, x, \zeta), \bar{x}\} d\lambda_j(a, \varepsilon, x, \zeta) \\ &= \sum_{j=1}^J \mu_j \int (1 - \zeta'_j(a, \varepsilon, x, \zeta)) b_{ss}(x) d\lambda_j(a, \varepsilon, x, \zeta) \end{aligned} \quad (3)$$

(6) Given policies and allocations, prices clear asset and labor markets:

$$\begin{aligned} K - B &= \sum_{j=1}^J \mu_j \int a d\lambda_j(a, \varepsilon, x, \zeta) \\ L &= \sum_{j=1}^J \mu_j \int \zeta'_j(a, \varepsilon, x, \zeta) e(\varepsilon) h_j(a, \varepsilon, x, \zeta) d\lambda_j(a, \varepsilon, x, \zeta) \end{aligned}$$

and the allocation satisfies the resource constraint (guaranteed by Walras' Law):

$$\sum_{j=1}^J \mu_j \int c_j(a, \varepsilon, x, \zeta) d\lambda_j(a, \varepsilon, x, \zeta) + G + K' = ZF(K, L) + (1 - \delta)K$$

(7) Given consumer policy functions, distributions across age j agents $\{\lambda_j\}_{j=1}^J$ are given recursively from the law of motion $T_j^* : \mathbf{M} \rightarrow \mathbf{M}$ for all $j \in \mathbf{J}$ such that T_j^* is given by:

$$\lambda_{j+1}(\mathcal{A} \times \mathcal{E} \times \mathcal{X} \times \mathcal{R}) = \sum_{\zeta \in \{0,1\}} \int_{\mathcal{A} \times \mathcal{E} \times \mathcal{X}} Q_j((a, \varepsilon, x, \zeta), \mathcal{A} \times \mathcal{E} \times \mathcal{X} \times \mathcal{R}) d\lambda_j$$

where $\mathcal{S} \equiv \mathcal{A} \times \mathcal{E} \times \mathcal{X} \times \mathcal{R} \subset \mathbf{S}$, and $Q_j : \mathbf{S} \times \mathcal{B}(\mathbf{S}) \rightarrow [0, 1]$ is a transition

function on $(\mathbf{S}, \mathcal{B}(\mathbf{S}))$ that gives the probability that an age- j agent with current state $\mathbf{s} \equiv (a, \varepsilon, x, \zeta)$ transits to the set $\mathcal{S} \subset \mathbf{S}$ at age $j + 1$. The transition function is given by:

$$Q_j((a, \varepsilon, x, \zeta), \mathcal{S}) = \begin{cases} s_j \cdot \pi_j(\mathcal{E}|\varepsilon)^\zeta & \text{if } a'_j(\mathbf{s}) \in \mathcal{A}, x'_j(\mathbf{s}) \in \mathcal{X}, \zeta'_j(\mathbf{s}) \in \mathcal{R} \\ 0 & \text{otherwise} \end{cases}$$

where agents that continue working and transition to set \mathcal{E} choose $\zeta'_j(\mathbf{s}) = 1$, while agents that transition from working life to retirement choose $\zeta'_j(\mathbf{s}) = 0$. For $j = 1$, the distribution λ_j reflects the invariant distribution $\pi_{ss}(\varepsilon)$ of initial labor productivity over $\varepsilon = (\kappa, \theta_1, 0, \epsilon_1)$.

- (8) Aggregate capital, governmental debt, prices and the distribution over consumers are stationary, such that $K' = K$, $B' = B$, $w' = w$, $r' = r$, and $\lambda'_j = \lambda_j$ for all $j \in \mathbf{J}$.

3.2 Infinitely Lived Agent Model

The infinitely lived agent model differs from the life cycle model in three ways. First, agents in the infinitely lived agent model have no mortality risk ($s_j = 1$ for all $j \geq 1$) and lifetimes are infinite ($J \rightarrow \infty$). Second, labor productivity no longer has an age-dependent component ($\theta_j = \bar{\theta}$ for all $j \geq 1$). Lastly, there is no retirement ($J_{ret} \rightarrow \infty$ such that $\zeta_j = 1$ for all $j \geq 1$) and there is no Social Security program ($\tau_{ss} = 0$ and $b_{ss}(x) = 0$ for all x).

Accordingly, we study a stationary recursive competitive equilibrium in which the initial endowment of wealth and labor productivity shocks no longer affects individual decisions and the distribution over wealth and labor productivity is time invariant.

Definition (Equilibrium): Given a government policy (G, B, B', Y) , a *stationary recursive competitive equilibrium* is (i) an allocation for consumers described by policy functions (c, a', h) and consumer value function V , (ii) an allocation for the representative firm (K, L) , (iii) prices (w, r) , and (v) a distribution over agents' state vector λ that satisfy:

(1) Given prices and policies, $V(a, \varepsilon)$ solves the following Bellman equation:

$$V(a, \varepsilon) = \max_{c, a', h} [u(c) - v(h)] + \beta \sum_{\varepsilon'} \pi(\varepsilon' | \varepsilon) V(a', \varepsilon') \quad (4)$$

$$\text{s.t.} \quad c + a' \leq we(\varepsilon)h + (1 + r)a + Y(y(h, a, \varepsilon))$$

$$a' \geq \underline{a}$$

with associated policy functions $c(a, \varepsilon)$, $a'(a, \varepsilon)$ and $h(a, \varepsilon)$.

(2) Given prices (w, r) , the representative firm's allocation minimizes cost.

(3) Government policies satisfy budget balance in [equation \(1\)](#), where aggregate income tax revenue is given by:

$$Y_y \equiv \int Y(y(h(a, \varepsilon), a, \varepsilon)) d\lambda(a, \varepsilon)$$

(4) Given policies and allocations, prices clear asset and labor markets:

$$K - B = \int a d\lambda(a, \varepsilon)$$

$$L = \int e(\varepsilon)h(a, \varepsilon) d\lambda(a, \varepsilon)$$

and the allocation satisfies the resource constraint (guaranteed by Walras' Law):

$$\int c(a, \varepsilon) d\lambda(a, \varepsilon) + G + K' = ZF(K, L) + (1 - \delta)K$$

(5) Given consumer policy functions, the distribution over wealth and productivity shocks is given recursively from the law of motion $T^* : \mathbf{M} \rightarrow \mathbf{M}$ such that T^* is given by:

$$\lambda'(\mathcal{A} \times \mathcal{E}) = \int_{\mathcal{A} \times \mathcal{E}} Q_j((a, \varepsilon), \mathcal{A} \times \mathcal{E}) d\lambda$$

where $\mathcal{S} \equiv \mathcal{A} \times \mathcal{E} \subset \mathbf{S}$, and $Q : \mathbf{S} \times \mathcal{B}(\mathbf{S}) \rightarrow [0, 1]$ is a transition function on $(\mathbf{S}, \mathcal{B}(\mathbf{S}))$ that gives the probability that an agent with current state $\mathbf{s} \equiv (a, \varepsilon)$ transits to the set $\mathcal{S} \subset \mathbf{S}$ in the next period. The transition

function is given by:

$$Q((a, \varepsilon), \mathcal{S}) = \begin{cases} \pi(\mathcal{E}|\varepsilon) & \text{if } a'(\mathbf{s}) \in \mathcal{A}, \\ 0 & \text{otherwise} \end{cases}$$

- (6) Aggregate capital, governmental debt, prices and the distribution over consumers are stationary, such that $K' = K$, $B' = B$, $w' = w$, $r' = r$, and $\lambda' = \lambda$.

3.3 Balanced Growth Path

Following [Aiyagari and McGrattan \(1998\)](#), we will further assume that total factor productivity, Z , grows over time at rate $g_z > 0$. In both the life cycle model and infinitely lived agent model, we will study a balanced growth path equilibrium in which all aggregate variables grow at the same rate as output. Denote the growth rate of output as g_y . Refer to [Appendix A.1](#) for a formal construction of the balanced growth path for this set of economies.

4 Calibration

In this section we calibrate the life cycle model and then discuss the parameter values that are different in the infinitely lived agent model. Overall, one subset of parameters are assigned values without needing to solve the model. These parameters are generally the same in both models. The other subset of parameters are estimated using a simulated method of moments procedure that minimizes the distance between model generated moments and empirical ones. We allow these parameters to vary across the models while matching the same moments in the two models. [Table 1](#) summarizes the target and value for each parameter.

Demographics: Agents enter the economy at age 21 (or model age $j = 1$) and exogenously die at age 100 (or model age $J = 81$). We set the conditional survival probabilities $\{s_j\}_{j=1}^J$ according to [Bell and Miller \(2002\)](#) and impose

$s_J = 0$. We set the population growth rate to $g_n = 0.011$ to match annual population growth in the US.

Production: Given that $Y = ZF(K, L)$, the production function is assumed to be Cobb-Douglas of the form $F(K, L) = K^\alpha L^{1-\alpha}$ where $\alpha = 0.36$ is the income share accruing to capital. The depreciation rate is to $\delta = 0.0833$ which allows the model to match the empirically observed investment-to-output ratio.

Preferences: The utility function is separable in the utility over consumption and disutility over labor (including retirement):

$$u(c) - v(h, \zeta') = \frac{c^{1-\sigma}}{1-\sigma} - \left(\chi_1 \frac{h^{1+\frac{1}{\gamma}}}{1+\frac{1}{\gamma}} + \zeta' \chi_2 \right).$$

Utility over consumption is a CRRA specification with a coefficient of relative risk aversion $\sigma = 2$, which is consistent with [Conesa et al. \(2009\)](#) and [Aiya-gari and McGrattan \(1998\)](#). Disutility over labor exhibits a constant intensive margin Frisch elasticity. We choose $\gamma = 0.5$ such that the Frisch elasticity consistent with the majority of the related literature as well as the estimates in [Kaplan \(2012\)](#).

We calibrate the labor disutility parameter χ_1 so that the cross sectional average of hours is one third of the time endowment. Finally, χ_2 is a fixed utility cost of earning labor income before retirement. The fixed cost generates an extensive margin decision through a non-convexity in the utility function. We choose χ_2 to match the empirical observation that seventy percent of the population has retired by the normal retirement age.

Labor Productivity Process: We take the labor productivity process from the estimates in [Kaplan \(2012\)](#) based on the estimates from the PSID data.¹⁰ The

¹⁰For details on estimation of this process, see Appendix E in [Kaplan \(2012\)](#). A well known problem with a log-normal income process is that the model generated wealth inequality does not match that in the data, primarily due to missing the fat upper tail of the distribution. However, [Röhrs and Winter \(2016\)](#) demonstrate that when the income process in an infinitely lived agent model is altered to match the both the labor earnings and wealth distributions (quintiles and gini coefficients), the change in optimal policy is relatively small, with approximately 30 percentage points due to changing the income process and the remaining 110 percentage points due to changing borrowing limits, taxes and invariant parameters (such as risk aversion, the Frisch elasticity, output growth rate and depreciation).

deterministic labor productivity profile, $\{\theta_j\}_{j=1}^{\bar{J}_{ret}}$, is (i) smoothed by fitting a quadratic function in age, (ii) normalized such that the value equals unity when an agent enters the economy, and (iii) extended to cover ages 21 through 70 which we define as the last period in which agents are assumed to be able to participate in the labor activities (\bar{J}_{ret}).¹¹ The permanent, persistent, and transitory idiosyncratic shocks to individual's productivity are normally distributed with zero mean. The remaining parameters are also set in accordance with the [Kaplan's \(2012\)](#) estimates: $\rho = 0.958$, $\sigma_\kappa^2 = 0.065$, $\sigma_\nu^2 = 0.017$ and $\sigma_\epsilon^2 = 0.081$.

Government: Consistent with [Aiyagari and McGrattan \(1998\)](#) we set government debt equal to two-thirds of output. We set government consumption equal to 15.5 percent of output consistent. This ratio corresponds to the average of government expenditures to GDP from 1998 through 2007.¹²

Income Taxation: The income tax function and parameter values are from [Gouveia and Strauss \(1994\)](#). The functional form is:

$$Y(y) = \tau_0 \left(y - (y^{-\tau_1} + \tau_2)^{-\frac{1}{\tau_1}} \right)$$

The authors find that $\tau_0 = 0.258$ and $\tau_1 = 0.768$ closely match the U.S. tax data. When calibrating the model we set τ_2 such that the government budget constraint is satisfied.

Social Security: We set the normal retirement age to 66. Consistent with the minimum and maximum retirement ages in the U.S. Social Security system, we set the interval in which agents can retire to the ages 62 and 70. The early retirement penalty and later retirement credits are set in accordance with the Social Security program. In particular, if agents retire up to three years before the normal retirement age agents benefits are reduced by 6.7 percent for each year they retire early. If they choose to retire four or five years before the normal retirement age benefits are reduced by an additional 5 percent

¹¹The estimates in [Kaplan \(2012\)](#) are available for ages 25-65.

¹²We exclude government expenditures on Social Security since they are explicitly included in our model.

Table 1: Calibration Targets and Parameters for Baseline Economy.

Description	Parameter	Value	Target or Source
Demographics			
Maximum Age	J	81 (100)	By Assumption
Min/Max Retirement Age	$\underline{J}_{ret}, \bar{J}_{ret}$	43, 51 (62, 70)	Social Security Program
Population Growth	g_n	1.1%	Conesa et al (2009)
Survival Rate	$\{s_j\}_{j=1}^J$	—	Bell and Miller (2002)
Preferences and Borrowing			
Coefficient of RRA	σ	2.0	Kaplan (2012)
Frisch Elasticity	γ	0.5	Kaplan (2012)
Coefficient of Labor Disutility	χ_1	55.3	Avg. Hours Worked = 1/3
Fixed Utility Cost of Labor	χ_2	1.038	70% retire by NRA
Discount Factor	β	1.012	Capital/Output = 2.7
Borrowing Limit	\underline{a}	0	By Assumption
Technology			
Capital Share	α	0.36	NIPA
Capital Depreciation Rate	δ	0.0833	Investment/Output = 0.255
Productivity Level	Z	1	Normalization
Output Growth	g_y	1.85%	NIPA
Labor Productivity			
Persistent Shock, autocorrelation	ρ	0.958	Kaplan (2012)
Persistent Shock, variance	σ_v^2	0.017	Kaplan (2012)
Permanent Shock, variance	σ_κ^2	0.065	Kaplan (2012)
Transitory Shock, variance	σ_ϵ^2	0.081	Kaplan (2012)
Mean Earnings, Age Profile	$\{\theta\}_{j=1}^{\bar{J}_{ret}}$	—	Kaplan (2012)
Government Budget			
Government Consumption	G/Y	0.155	NIPA Average 1998-2007
Government Savings	B/Y	-0.667	NIPA Average 1998-2007
Marginal Income Tax	τ_0	0.258	Gouveia and Strauss (1994)
Income Tax Progressivity	τ_1	0.786	Gouveia and Strauss (1994)
Income Tax Progressivity	τ_2	4.541	Balanced Budget
Social Security			
Payroll Tax	τ_{ss}	0.103	Social Security Program
SS Replacement Rates	$\{\tau_{ri}\}_{i=1}^3$	See Text	Social Security Program
SS Replacement Bend Points	$\{b_i^{ss}\}_{i=1}^3$	See Text	Social Security Program
SS Early Retirement Penalty	$\{\kappa_i\}_{i=1}^3$	See Text	Social Security Program

for these years. If agents choose to delay retirement past normal retirement age then their benefits are increased by 8 percent for each year they delay. The marginal replacement rates in the progressive Social Security payment schedule ($\tau_{r1}, \tau_{r2}, \tau_{r3}$) are also set at their actual respective values of 0.9, 0.32 and 0.15. The bend points where the marginal replacement rates change (b_1^{ss} ,

b_2^{ss}, b_3^{ss}) and the maximum earnings (\bar{x}) are set equal to the actual multiples of mean earnings used in the U.S. Social Security system so that b_1^{ss}, b_2^{ss} and $b_3^{ss} = \bar{x}$ occur at 0.21, 1.29 and 2.42 times average earnings in the economy. We set the payroll tax rate, τ_{ss} such that the program's budget is balanced. In our baseline model the payroll tax rate is 10.3 percent, roughly equivalent with the statutory rate.¹³

Infinitely Lived Agent Model: The infinitely lived agent model does not have a age-dependent wage profile. For comparability across models, we replace the age-dependent wage profile with the population-weighted average of θ_j 's, such that $\bar{\theta} = \sum_{j=1}^{\bar{J}_{ret}} (\mu_j / \sum_{j=1}^{\bar{J}_{ret}} \mu_j) \theta_j \approx 1.86$.¹⁴ In the absence of a retirement decision, we set $\chi_2 = 0$. Lastly, we recalibrate the parameters (β, χ) to the same targets as in the life cycle model and choose τ_2 to balance the government's budget.

5 Quantitative Effects of the Life Cycle on Optimal Policy

Having described how we use external data to discipline the models' structural parameters, we use the calibrated model to measure optimal policy across the life cycle and infinitely lived agent models. Then we perform a series of counterfactual experiments to highlight the mechanisms that generate differences in optimal policy across the models.

¹³Although the payroll tax rate in the U.S. economy is slightly higher than our calibrated value, the OASDI program includes additional features outside of the retirement benefits.

¹⁴When calibrating the stochastic process for idiosyncratic productivity shocks, we use the same process in the both the life cycle and infinitely lived agent models. Using the same underlying process will imply that cross-sectional wealth inequality will be different across the two models. One reason is that the life cycle model will have additional cross-sectional inequality due to the humped shaped savings profiles, which induces the accumulation, stationary, and deaccumulation phases. We view these difference in inequality as a fundamental difference between the two models and, therefore, choose not to specially alter the infinitely lived agent model to match a higher level of cross-sectional inequality.

5.1 Optimal Public Policy

The government maximizes social welfare by choosing a budget feasible level of public savings, B , subject to allocations being a stationary recursive competitive equilibrium. We consider an ex-ante Utilitarian social welfare criterion that evaluates the expected lifetime utility of an agent that has yet to enter the steady state economy.¹⁵ For the life cycle model, the government's welfare maximization problem is:

$$S_J(V_1, \lambda_1) \equiv \max_B \left\{ \int V_1(a, \varepsilon, x, \zeta; B) d\lambda_1(a, \varepsilon, x, \zeta; B) \quad \text{s.t.} \quad (1), (3) \right\}$$

where the value function $V_1(\cdot; B)$, distribution function $\lambda_1(\cdot; B)$ and policy functions embedded in equations (1) and (3) are determined in competitive equilibrium and depend on the government's choice of public savings. Furthermore, $B' = B$ in steady state. Since the distribution of taxable income and tax revenues depend on public savings, we adjust the Social Security payroll tax rate τ_{ss} to ensure that Social Security is self-financing and, furthermore, adjust the income tax parameter τ_0 to ensure that the government budget is balanced.¹⁶

For the infinitely lived agent model, the government's welfare maximization problem is:

$$S_\infty(V, \lambda) \equiv \max_B \left\{ \int V(a, \varepsilon; B) d\lambda(a, \varepsilon; B) \quad \text{s.t.} \quad G = rB + Y_y(\tau_0, B) \right\}$$

The infinitely lived agent model government's welfare maximization problem is nearly identical to that of the life cycle model's, except that the value function and distribution function do not depend on age and there is no Social Security program, so that equation (3) does not define the feasible set.

¹⁵Our analysis focuses on welfare across steady states. This analysis omits the transitional costs between steady states which can be large. See [Domeij and Heathcote \(2004\)](#), [Fehr and Kindermann \(2015\)](#) and [Dyrda and Pedroni \(2016\)](#).

¹⁶We choose to use τ_0 to balance the government budget instead of the other income taxation parameters (τ_1, τ_2) so that the average income tax rate is used to clear the budget, as opposed to changing in the progressivity of the income tax policy. The average tax rate is the closest analogue to the flat tax that [Aiyagari and McGrattan \(1998\)](#) use to balance the government's budget in their model.

We find that the two models generate starkly different optimal policies, which are reported in [Table 2](#). In the infinitely lived agent model, the government optimally holds debt equal to 22 percent of output.¹⁷ In the life cycle model, on the other hand, the government optimally holds savings equal to 59 percent of output. Thus, including life cycle features causes optimal policy to switch from public debt to savings, with an 80 percentage point swing in optimal policy.

Table 2: Prices and Aggregates Across Models

	Life Cycle			Infinitely Lived		
	Base.	Opt.	% Δ	Base.	Opt.	% Δ
Public Savings/Output	-0.67	0.59	189.0	-0.67	-0.22	67.5
Private Savings/Output	3.37	2.42	-28.2	3.35	2.96	-11.7
Capital/Output	2.70	3.01	11.5	2.70	2.74	1.9
Output	0.93	1.01	8.6	1.16	1.17	1.5
Labor	0.53	0.54	2.2	0.66	0.67	0.4
Interest Rate	5.0%	3.6%	-1.4	5.0%	4.8%	-0.2
Wage	1.12	1.19	6.3	1.12	1.13	1.0

5.2 Welfare Decomposition

While the infinitely lived agent model prescribes that the government hold public debt, the life cycle model's optimal policy prescribes holding public savings. What is the welfare loss from incorrectly implementing a public debt policy?

We quantify the welfare consequence of ignoring life cycle features and, as a consequence, adopting a public debt instead of a public savings policy. To do so, suppose that the government implements the optimal debt policy from an infinitely lived agent economy when the true economy is a life cycle economy. We then measure the welfare loss from implementing a suboptimal

¹⁷This is generally consistent with [Aiyagari and McGrattan's \(1998\)](#) optimal policy. This paper assumes a different stochastic process governing labor productivity, a different utility function, non-linear income taxation and different parameter values. A quantitative decomposition of these model differences are available upon request.

debt policy using *consumption equivalent variation* (CEV). CEV is the percent of lifetime consumption that an agent would be willing to pay, ex ante, in order to live in an economy with an optimal public savings policy instead of a suboptimal public debt policy.

Table 3 reports the consumption equivalent variation. We find that an 80 percentage point difference in fiscal policy corresponds to a welfare loss of 0.42 percent of expected lifetime consumption. The welfare loss is economically significant, demonstrating that ignoring life cycle features when determining optimal debt policy will have nontrivial welfare effects. The same 80 percentage point change to government policy in the infinitely lived agent model leads to much smaller welfare effects. In particular, an infinitely lived agent would only sacrifice 0.04 percent of lifetime consumption in order to live in the economy in which the government holds optimal debt instead of 59 percent of output in public savings.

Table 3: Welfare Decompositions

(% Change)	Life Cycle	Infinitely Lived
Overall CEV	0.42	-0.04
Level (Δ_l)	0.92	-0.70
Consumption (Δ_{C_l})	1.36	0.90
Hours (Δ_{H_l})	-0.43	-1.58
Distribution (Δ_d)	-0.50	0.66
Consumption (Δ_{C_d})	0.08	-0.20
Hours (Δ_{H_d})	-0.58	0.86

The Life Cycle Model welfare decomposition compares allocations under a -22% public debt-to-output and the optimal 59% public savings-to-output ratio. The Infinitely Lived Agent Model welfare decomposition compares allocations under the optimal -22% public debt-to-output and a 59% public savings-to-output ratio. The Level and Distribution decompositions are given by $100((1 + \Delta_{C_l})(1 + \Delta_{H_l}) - 1)$ and $100((1 + \Delta_{C_d})(1 + \Delta_{H_d}) - 1)$.

The welfare gains from implementing optimal policy reflect the government's desire to improve the aggregate resources available to agents and the allocation of those resources across agents. In order to characterize these wel-

fare effects, we decompose the consumption equivalent variation (denoted Δ_{CEV}) into a *level effect* (Δ_l) and a *distribution effect* (Δ_d) as follows:¹⁸

$$(1 + \Delta_{CEV}) = \underbrace{[(1 + \Delta_{C_l})(1 + \Delta_{H_l})]}_{\equiv (1 + \Delta_l)} \cdot \underbrace{[(1 + \Delta_{C_d})(1 + \Delta_{H_d})]}_{\equiv (1 + \Delta_d)}.$$

The level effect measures the average agent's change in welfare as a result of changes in aggregate consumption (Δ_{C_l}) and aggregate hours (Δ_{H_l}). The level effect captures the welfare change for a fictitious "representative agent," absent distributional concerns of policy. On the other hand, the distribution effect measures the remaining change in welfare that results from a change in the distribution of consumption (Δ_{C_d}) and hours (Δ_{H_d}) across agents.¹⁹

Adopting public savings has differential welfare effects across the two models. Table 3 reports that the 0.42 percent welfare improvement from adopting public savings in the life cycle model can be decomposed into a 0.92 percent increase from the level effect and a partially offsetting 0.50 percent decrease from the distribution effect. The opposite holds for adopting public savings in the infinitely lived agent model, where the 0.04 percent welfare loss corresponds to a 0.70 percent decrease in the level effect and 0.66 percent increase from the distribution effect. These differences in level and distribution effects reflect the varying welfare impact of competing mechanisms across models.

The level effect reflects a difference in the efficacy of the insurance channel across models. To see this, first note that adopting public savings induces a higher wage and a lower interest rate. The higher wage encourages additional labor hours, which increases the resources available for agents' consumption (as seen in Figure 2 for the life cycle model) but worsens total disutility from

¹⁸More generally, we follow Floden (2001) in characterizing four components of the CEV: a level effect (Δ_L), an insurance effect (Δ_I), a redistribution effect (Δ_R) and a labor hours effect (Δ_H). We combine the insurance and redistribution effects to form the "distribution effect". Appendix A.2 formally derives the decomposition.

¹⁹Note that the life cycle model only assumes initial heterogeneity with respect to the permanent and transitory components of labor productivity, but not initial wealth heterogeneity. While allowing for heterogeneity in the initial wealth distribution could generate a larger distribution effect in welfare changes, the PSID and SCF document low levels and relatively small dispersion in individuals' wealth upon entering the labor market.

hours worked. However, [Table 3](#) reports that the percent change in utility from increased aggregate consumption is higher in the life cycle model (1.36) than in the infinitely lived agent model (0.90), despite a larger percent increase in labor disutility in the latter. To account for the relatively smaller consumption increase in the infinitely lived agent model, recall that the lower interest rate discourages private savings in each model. In the infinitely lived agent model, however, the policy also reduces *ex ante* average wealth. This is because, by the nature of living infinite lifespans, aggregate savings is equivalent to *ex ante* wealth. Therefore, the lower interest rate worsens an infinitely lived agent's *ex ante* self-insurance and a larger fraction of the population must sacrifice consumption due to binding liquidity constraints.²⁰ In contrast, the lower interest rate has no effect on initial allocations in the life cycle model because initial wealth is zero and does not respond to prices.²¹ We provide quantitative evidence for this mechanism in [Section 5.3.1](#).

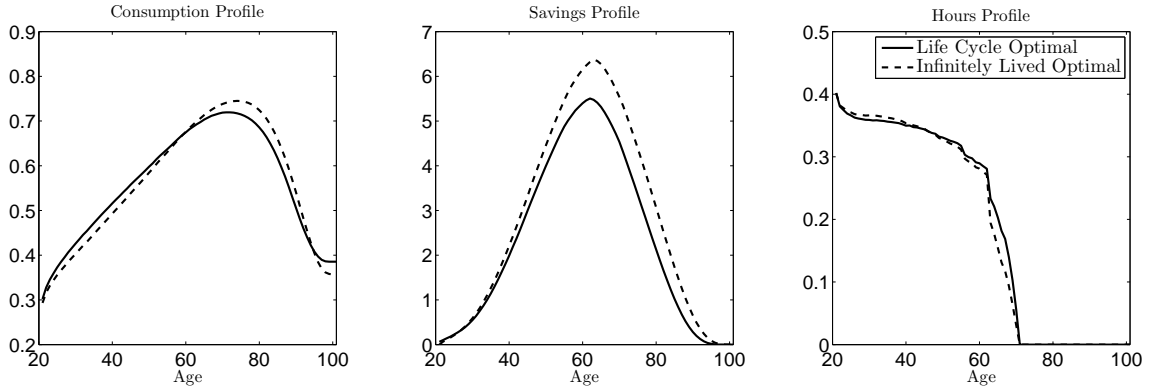


Figure 2: Solid lines are cross-sectional averages for consumption, savings, and hours by age in the life cycle economy under its optimal public savings policy. The dashed lines are cross-sectional averages for the suboptimal debt policy from the infinitely lived agent economy.

Finally, the distribution effect corresponds to the inequality channel in both models. Yet, a higher wage has different effects on inequality in the

²⁰Relative to [Floden \(2001\)](#), the effect of policy on insurance is usually defined as a distribution effect. However, in order to compare model outcomes, we measure it as an average effect on consumption and hours that is captured by the level effect.

²¹The lower interest rate may decrease average savings across the lifetime, however it does not have as large of a welfare effect since it does not change the initial distribution.

life cycle and infinitely lived agent models. In the life cycle model, since labor earnings contribute more to total income inequality than asset income does, a higher wage exacerbates existing lifetime total income inequality. In the infinitely lived agent model, the opposite holds true: since asset income contributes more to total income inequality, a higher wage alleviates existing lifetime total income inequality. Accordingly, the negative distribution effect in the life cycle model reflects greater income inequality while the positive distribution effect in the infinitely lived agent model reflects lower income inequality. We provide quantitative evidence for this mechanism in [Section 5.3.2](#).

5.3 Life Cycle Features

There are three main differences between the life cycle and infinitely lived agent models: (i) agents in the life cycle model experience an accumulation phase while agents in the infinitely lived agent model experience a perpetual stationary phase, (ii) age-dependent features in the life cycle model, such as mortality risk, an age-dependent wage profile, retirement and Social Security, do not exist in the infinitely lived agent model and (iii) the lifespan is different in the two models. We begin by demonstrating that the introduction of the accumulation phase in the life cycle model can more than explain the differences in optimal policies between the two models. Then we systematically decompose the effects of each of the three model differences on optimal policy.

5.3.1 The Accumulation Phase

This section quantifies the importance of the accumulation phase for explaining the difference in optimal policies between the life cycle and infinitely lived agent models. We do this by constructing an approximation to the infinitely lived agent economy that features an accumulation phase. Relative to the infinitely lived agent model, the counterfactual model mainly differs from the infinitely lived agent model in that agents are endowed with zero wealth. In order to activate the accumulation phase we assume agents have

finite lifespans. However, we assume that agents die at the end of $J = 1000$ periods, a sufficiently large terminal age to mimic the infinitely lived agent model. Therefore, by construction, the fundamental difference between the counterfactual model and the infinitely lived agent model is the accumulation phase.²²

Using the calibrated counterfactual model, we conduct a computational experiment to isolate the impact of the accumulation phase on optimal policy. Suppose that the government chooses policy according to an alternative social welfare criterion that places less weight on the flow of utility during youth than does the ex ante Utilitarian welfare criterion. In particular, suppose that the alternative social welfare criterion only incorporates the expected present value of utility after a given age $j^* > 1$, and ignores the flow of utility from ages 1 to $j^* - 1$. Government policy, therefore, maximizes agents' expected utility as of age j^* , subject to allocations being determined in competitive equilibrium:

$$\tilde{S}(V_{j^*}, \lambda_{j^*}) \equiv \max_B \left\{ \int V_{j^*}(a, \varepsilon; B) d\lambda_{j^*}(a, \varepsilon; B) \quad \text{s.t.} \quad G = rB + Y_y(\tau_0, B) \right\}.$$

Figure 3 plots the optimal policy under this alternative welfare criterion as a function of the percent of the lifetime that threshold age, j^* , represents. We observe that optimal policy monotonically decreases from the public savings to output ratio of 2.35 when all of the lifetime is considered, to an optimal debt policy when the social welfare function ignores at least 5.2 percent of agents' early lifetime. Across models, higher public debt (lower public savings) crowds out the productive capital stock and leads to a higher interest rate. The higher interest rate encourages agents to save, which improves self insurance. When the age threshold is small, the government includes agents' utility during the accumulation phase in its welfare maximization calculation. As a result, agents' welfare improvement from accumulating more precautionary savings is offset by the utility cost of accumulating that savings.

²²Neither the infinitely lived nor the counterfactual model feature any age-dependent features (e.g., no mortality risk, no age-dependent wage profile, no retirement and no Social Security). In order to make quantitative comparisons across models, the counterfactual model's parameters are recalibrated to match all relevant the targets described in Section 4.

However, when the age threshold is large, the government ignores the flow of utility for agents in the accumulation phase and there is only a large welfare improvement from agents living with more self insurance. The right panel of Figure 3 shows that ignoring at least 5.2 percent of agents' early lifetime corresponds to ignoring at least 69 percent of the accumulation phase.

The experiment shows that the existence of an accumulation phase is crucial to the optimality of public savings. Without the accumulation phase, the benefits of the insurance channel strengthen and lead to the optimality of public debt. In contrast, when the accumulation phase is incorporated, the benefits from the insurance channel are smaller and public savings is optimal.

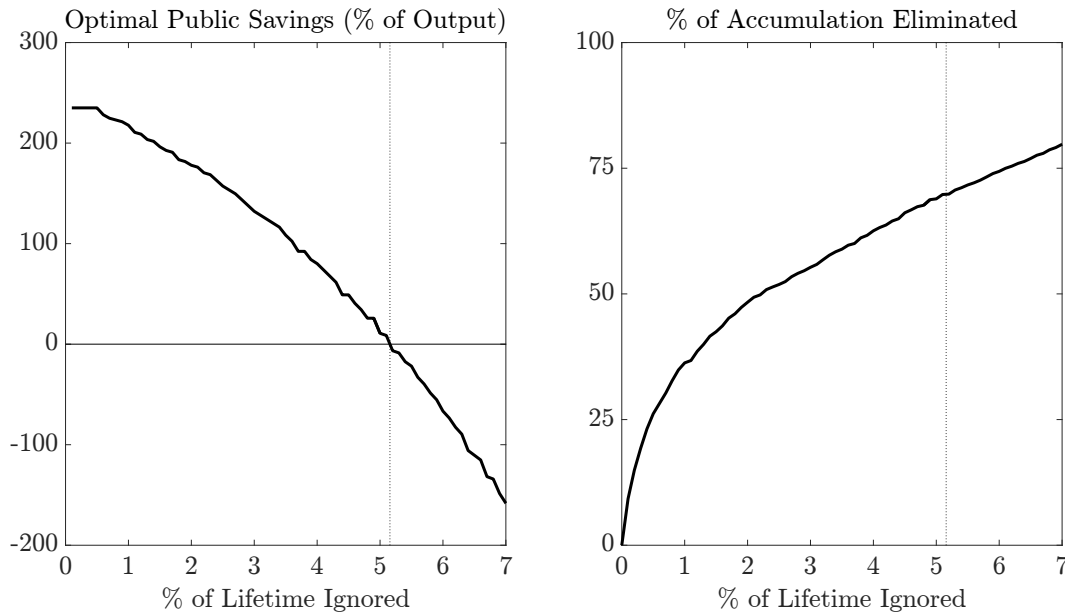


Figure 3: The left panel graphs the optimal public savings to output ratio (y-axis) associated with ignoring a given percent of early life utility flows (x-axis). The percent of "Lifetime Ignored" is measured as $100 \cdot (j^*/J)$, using the given value of j^* and $J = 1000$. The right panel graphs the percent of accumulation that is eliminated under the optimal policy associated with ignoring a given percent of early life utility flows. The percent of eliminated wealth accumulation is defined as the average private savings of j^* -age agents relative to the peak average savings and converted to a percent, given a particular optimal public savings policy. The vertical dashed line demarcates the percent of early lifetime utility ignored at which optimal policy switches from public savings to debt.

Table 4: Optimal Public Savings-to-Output Ratios

Life Cycle	<u>Counterfactuals</u>		
	No Age Features (81 periods)	Long Lifespan (401 periods)	Infinitely Lived
0.59	2.00	2.48	-0.22

5.3.2 Decomposing the Effects of Life Cycle Features

Apart from the accumulation phase, there are two remaining differences between the life cycle and infinitely lived agent models: lifespan and age-dependent features (e.g., mortality risk, age-dependent wage profile, retirement and Social Security). Next, we quantify the effect of each of these differences on optimal policy. Unlike removing the accumulation phase, we find that removing lifespan and age-dependent features shifts optimal policy towards *more* public savings.

In order to characterize the individual effects of these differences on optimal policy between the life cycle and infinitely lived agent models, we construct two counterfactual economies. The first is the "No Age-Dependent Features" economy, which is a version of the life cycle model that excludes all age-dependent features (e.g., no mortality risk, no age-dependent wage profile, no retirement and no Social Security) while maintaining the lifespan of $J = 81$ periods. The second is the "Long Life" economy, which removes age-dependent model features and also extends agents' lifetime to $J = 401$ periods.²³

Table 4 reports optimal policies in the benchmark life cycle, infinitely lived, and counterfactual models. First, comparing the baseline life cycle model and "No Age-Dependent Features" economy isolates the effect of age-dependent features, which leads to an increase in the working lifetime due to the removal of retirement and mortality. We find that the optimal savings-to-output shifts from 59 to 200 percent. Comparing the "No Age-Dependent Features" and "Long Life" counterfactual economies isolates the effect of further increasing

²³In order to make quantitative comparisons across models, each counterfactual model's parameters are recalibrated to match all relevant the targets described in Section 4.

Table 5: Income Composition and Inequality

	<u>Counterfactuals</u>		
	Life Cycle	No Age Features (81 periods)	Long Lifespan (401 periods)
(a) Asset Income Inequality in Baseline Calibration			
Coefficient of Variation	0.33	0.34	0.49
Gini Coefficient	0.19	0.20	0.28
(b) Lifetime Total Income Inequality			
<i>Coefficient of Variation</i>			
Baseline	0.36	0.32	0.31
Optimal	0.35	0.30	0.27
% Change	-1.8%	-7.1%	-13.8%
<i>Gini Coefficient</i>			
Baseline	0.20	0.18	0.17
Optimal	0.19	0.16	0.15
% Change	-2.0%	-6.9%	-12.0%

agents' working lifetime and lifespan. This effect additionally increases the optimal savings-to-output from 200 to 248 percent. Finally, comparing the "Long Life" economy with the infinitely lived agent model highlights the effect of the accumulation phase on optimal policy, which switches optimal policy from savings to debt-to-output of 22 percent.

Removing age-dependent features and extending agents' lifespan generates increases in optimal public savings by lengthening the span of life that agents spend working. In the life cycle model, there is a tendency for wealth inequality to increase with an extension of agents' expected working lifespan and, in turn, this generates a greater amount of inequality in lifetime asset income. Table 5(a) reports that, indeed, measures of lifetime asset income inequality (the Gini coefficient and the coefficient of variation), increase under the baseline calibration when these two features are removed.²⁴ Likewise, un-

²⁴To construct inequality measures, we use lifetime asset income as a share of lifetime total

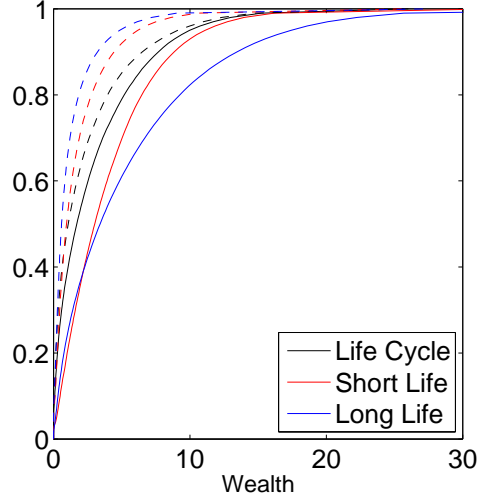


Figure 4: Cumulative Distribution Function for Wealth. Solid lines represent the baseline economy and dashed lines represent economies with optimal policy.

der the baseline policy, the cumulative distribution functions for wealth across all agents (see Figure 4) demonstrate that wealth becomes more unequal when either of these features are removed. In contrast, Table 5(b) demonstrates that lifetime *total* income inequality tends to decrease. Therefore, interest income becomes a larger source of overall income inequality when both age-dependent features are removed and the lifespan is extended.

Because of risk aversion, agents dislike inequality and thus policy has a role to improve welfare by reducing this income inequality. In the life cycle and counterfactual models, moving from public debt to public savings increases the wage and decreases the interest rate. This increases lifetime income inequality from savings and decreases lifetime income inequality from labor earnings. Thus, optimal policy must weigh this trade-off. Asset income contributes more to lifetime total income inequality when age-dependent features are removed and lifespan is extended. Accordingly, shifting toward a higher level of public savings will reduce lifetime total income inequality. The

income: $\sum_{j=1}^J s_j \left(\frac{1}{1+r}\right)^{j-1} ra_j / \left(\sum_{j=1}^J s_j \left(\frac{1}{1+r}\right)^{j-1} we_j h_j + \sum_{j=1}^J s_j \left(\frac{1}{1+r}\right)^{j-1} ra_j\right)$. For the No Age-Dependent Features and Long Lifespan counterfactual models, there is no mortality risk so that $s_j = 1$ for all $j = 1, \dots, J$.

change in the wealth distribution in [Figure 4](#) and the total lifetime income inequality measures in [Table 5\(b\)](#) demonstrate that, in fact, adopting an optimal public savings policy reduces both lifetime asset income and total income inequality. Thus, overall, eliminating age-dependent features and extending the lifespan both cause an increase in the optimal level of public savings due to the inequality channel.

Finally, the primary difference between the Long Life counterfactual model and the infinitely lived agent model is the existence of an accumulation phase. Despite their other common features (e.g., no age-dependent features, and long or infinite lifetimes), the infinitely lived agent model features a starkly different optimal policy of public debt as opposed to public savings. As [Section 2](#) explained, the existence of an accumulation phase mitigates the efficacy of the insurance channel while extending agents' working lifetime further enforces the inequality channel. Thus, when comparing the life cycle and the infinitely lived agent models, the existence of age-dependent features and a shorter lifespan drive optimal policy toward public debt while the existence of the accumulation phase drives optimal policy toward public savings. Overall, we find that the effects of the accumulation phase dominate the effects of other life cycle model features on optimal policy, thereby ultimately resulting in the optimality of public savings.

6 Conclusion

This paper measured the optimal quantity of public debt in a variant of the incomplete markets model that allows for an explicit life cycle. We find that it is optimal for the government to hold *savings* equal to 59% of output when life cycle features are included. In contrast, we find that it is optimal for the government to hold *debt* equal to 22% of output when these life cycle features are excluded. Furthermore, there are economically significant welfare consequences from not accounting for life cycle features when determining the optimal policy. We find that if a government implemented the infinitely lived agent model's optimal 22% debt-to-output policy in the life cycle model, then life cycle agents would be worse off by nearly one-half percent of expected

lifetime consumption.

The substantial difference in optimal policies across the two models is primarily due to differences in the effectiveness and benefit of public debt encouraging agents to hold precautionary savings. Generally, higher government debt (or decreasing government savings) tends to crowd out the stock of productive capital, and leads to a higher interest rate which encourages agents to hold more savings. However, this channel is significantly less beneficial in the life cycle model relative to the infinitely lived agent model. This is because, agents in the infinitely lived agent model do not experience an accumulation phase but instead experience a perpetual stationary phase in which agents have accumulated a target level of assets, around which savings fluctuates. If the government holds more public debt, then the *steady state* level of aggregate savings is larger and the average agent has more wealth *ex ante*. In contrast, life cycle agents enter the economy with zero wealth and immediately begin an accumulation phase, in which agents accumulate wealth for precautionary reasons and to finance post-retirement consumption. Thus, although changes in the interest rate may increase the level of savings in the stationary phase for life cycle agents, these agents' initial wealth will not respond to policy and agents still need to accumulate this wealth during the first phase of their lifetimes. Ultimately, this significantly reduces the benefit of government debt in the life cycle model.

When using quantitative models to answer economic questions, economists are constantly faced with a trade-off between tractability and realism. Our results demonstrate that when examining the welfare consequences of public debt or savings, it is not without loss of generality to utilize the more tractable infinitely lived agent model instead of a life cycle model.

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A Appendix

A.1 Construction of the Balanced Growth Path

We construct the Balanced Growth Path in multiple parts. First we construct the Balanced Growth Path using aggregates from the models. Then, we construct the Balanced Growth Path using individual agents' allocations. The last two sections develop the Balanced Growth Path for any features unique to the infinitely lived agent or life cycle models.

A.1.1 Aggregate Conditions

Balanced Growth Path: A Balanced Growth Path (BGP) is a sequence

$$\{C_t, A_t, Y_t, K_t, L_t, B_t, G_t\}_{t=0}^{\infty}$$

such that (i) for all $t = 0, 1, \dots$ $C_t, A_t, Y_t, K_t, B_t, G_t$ grow at a constant rate g ,

$$\frac{Y_{t+1}}{Y_t} = \frac{C_{t+1}}{C_t} = \frac{A_{t+1}}{A_t} = \frac{K_{t+1}}{K_t} = \frac{B_{t+1}}{B_t} = \frac{G_{t+1}}{G_t} = 1 + g$$

(ii) per capita variables all grow at the same constant rate g_w :

$$\frac{Y_{t+1}/N_{t+1}}{Y_t/N_t} = \frac{C_{t+1}/N_{t+1}}{C_t/N_t} = \frac{A_{t+1}/N_{t+1}}{A_t/N_t} = \frac{K_{t+1}/N_{t+1}}{K_t/N_t} = \frac{B_{t+1}/N_{t+1}}{B_t/N_t} = \frac{G_{t+1}/N_{t+1}}{G_t/N_t} = 1 + g_w$$

and (iii) hours worked per capita are constant:

$$\frac{L_{t+1}}{N_{t+1}} = \frac{L_t}{N_t} = \frac{L_0}{N_0}$$

Denote time 0 variables without a time subscript, for example $L \equiv L_0$.

Growth Rates: Let all growth derive from TFP $g_z > 0$ and population $g_n > 0$ growth. Then on a balanced growth path we assume:

$$Z_t = (1 + g_z)^t Z$$

$$N_t = (1 + g_n)^t N$$

where z and N are steady state values. Then, growth in labor is:

$$\frac{L_{t+1}}{L_t} = \frac{L_{t+1}/N_{t+1}}{L_t/((1+g_n)N_t)} = 1 + g_n$$

In steady state $Y = ZK^\alpha L^{1-\alpha}$. Let output growth be given by $g > 0$. Therefore the production function gives:

$$Y_t = Z_t K_t^\alpha L_t^{1-\alpha} \implies (1+g) = (1+g_z)^{\frac{1}{1-\alpha}} (1+g_n)$$

Lastly, from parts (ii) and (iii) of the Balanced Growth Path definition, we can solve for the growth of per capita variables:

$$\frac{Y_{t+1}/N_{t+1}}{Y_t/N_t} = \frac{Z_{t+1}}{Z_t} \left(\frac{K_{t+1}/N_{t+1}}{K_t/N_t} \right)^\alpha \left(\frac{L_{t+1}/N_{t+1}}{L_t/N_t} \right)^{1-\alpha} \implies (1+g_w) = (1+g_z)^{\frac{1}{1-\alpha}}$$

Prices: From Euler's theorem we know:

$$Y_t = \alpha Y_t + (1-\alpha)Y_t = (r_t + \delta)K_t + w_t L_t$$

Accordingly, the wage and interest rate depend on the capital-labor ratio. Growth in the capital-labor ratio is:

$$\frac{K_{t+1}/L_{t+1}}{K_t/L_t} = (1+g_z)^{\frac{1}{1-\alpha}} = 1 + g_w$$

Therefore, the growth rate for the wage is:

$$\frac{w_{t+1}}{w_t} = \frac{Z_{t+1}}{Z_t} \cdot \left(\frac{K_{t+1}/L_{t+1}}{K_t/L_t} \right)^\alpha = 1 + g_w$$

and the growth rate for the interest rate is:

$$\frac{r_{t+1} + \delta}{r_t + \delta} = \frac{Z_{t+1}}{Z_t} \cdot \left(\frac{K_{t+1}/L_{t+1}}{K_t/L_t} \right)^{\alpha-1} = 1$$

Therefore wages grow while interest rates do not.

Equilibrium Conditions: The detrended *asset market clearing condition* is:

$$K_t = A_t + B_t \implies K = A - B$$

The detrended *resource constraint* is:

$$C_t + K_{t+1} + G_t = Y_t + (1 - \delta)K_t \implies C + (g + \delta)K + G = Y$$

and the detrended *government budget constraint* is:

$$G_t + rB_t = T_t + B_{t+1} - B_t \implies G + (r - g)B = T$$

A.1.2 Individual Conditions

Preferences: We assume that labor disutility has a time-dependent component. Specifically, we assume labor disutility grows at the same rate as the utility over consumption, such that $v_{t+1}(h) = (1 + g_w)^{1-\sigma} v_t(h)$. Therefore, total utility is:

$$U_t(c_t, h_t) = u(c_t) - v_t(h_t) = \left[(1 + g_w)^{1-\sigma} \right]^t (u(c) - v(h)).$$

Social Security: In order for the AIME to grow at the same rate as the wage, we assume a cost of living adjustment (COLA) on Social Security taxes and payments. For social security taxes, the cap on eligible income grows at the rate of wage growth, $\bar{x}_t = (1 + g_w)^t \bar{x}$. Furthermore, base payment bend points $b_{i,t}^{ss} = (1 + g_w)^t b_i^{ss}$ and base payment values $\tau_{r,i,t} = (1 + g_w)^t \tau_{r,i}$ for $i = 1, 2, 3$.

Tax Function: On a Balanced Growth Path, (c_t, a'_{t+1}, a_t) and \tilde{y}_t must all grow at the same rate as the wage. Furthermore, the tax function must grow at the same rate as the wage. Recalling the tax function, $Y_t(\tilde{y}_t)$, τ_2 must grow at the same rate as $\tilde{y}_t^{-\tau_1}$. Rewrite as:

$$Y_t(\tilde{y}_t) = \tau_0 \left((1 + g_w)^t \tilde{y} - \left([(1 + g_w)^t]^{-\tau_1} \tilde{y}^{-\tau_1} + [(1 + g_w)^t]^{-\tau_1} \tau_2 \right)^{-\frac{1}{\tau_1}} \right) = (1 + g_w)^t Y(\tilde{y})$$

Individual Budget Constraint: An agent's time t budget constraint is:

$$c_t + a'_{t+1} \leq w_t \varepsilon_t h_t + (1 + r_t) a_t - T_t(\cdot)$$

$$c + (1 + g_w) a' \leq w \varepsilon h + (1 + r) a - T(\cdot)$$

where $\{c, a', a, h, w, r, \varepsilon\}$ are stationary variables. Given that the tax function $Y(\tilde{y})$ grows at rate g_w , so will the transfer function $T(h, a, \varepsilon)$ in the infinitely lived agent model. Furthermore, given that the Social Security program $\{\bar{x}, b_i^{ss}, \tau_{r,i}\}$ grows at rate g_w , so will the transfer $T(h, a, \varepsilon, x, \zeta')$ function in the life cycle model.

A.1.3 Life Cycle Model

Individual Problem: On the balanced growth path of the life cycle model, the stationary dynamic program is:

$$V_j(a, \varepsilon, x, \zeta) = \max_{c, a', h, \zeta'} [u(c) - \zeta' v(h)] + [\beta s_j (1 + g_w)^{1-\sigma}] \sum_{\varepsilon'} \pi_j(\varepsilon' | \varepsilon) V_{j+1}(a', \varepsilon', x', \zeta')$$

$$\text{s.t.} \quad c + (1 + g_w) a' \leq \zeta' w \varepsilon(\varepsilon) h + (1 + r)(a + Tr) + T(h, a, \varepsilon, x, \zeta')$$

$$a' \geq \underline{a}$$

$$\zeta' \in \{\mathbb{1}(j < J_{ret}), \mathbb{1}(j \leq \bar{J}_{ret}) \cdot \zeta\}$$

Distributions: For j -th cohort at time t , the measure over $(a, \varepsilon, x, \zeta)$ is given by:

$$\begin{aligned} \lambda_{j,t}(a_t, \varepsilon, x_t, \zeta) &= \lambda_{j,t-1} \left(\frac{a_t}{1 + g_w}, \varepsilon, \frac{x_t}{1 + g_w}, \zeta \right) (1 + g_n) \\ &= \lambda_{j,t-m} \left(\frac{a_t}{(1 + g_w)^m}, \varepsilon, \frac{x_t}{(1 + g_w)^m}, \zeta \right) (1 + g_n)^m \quad \forall m \leq t \\ &= \lambda_j(a, \varepsilon, x, \zeta) N_{t-j+1}. \end{aligned}$$

Therefore, $\lambda_j(a, \varepsilon, x, \zeta)$ is a stationary distribution over age j agents that integrates to one.

Aggregation: Aggregate consumption in the life cycle model is constructed as follows. Define the relative size of cohorts as $\mu_1 = 1$ and:

$$\mu_{j+1} = \frac{N_{t-j}}{N_t} \cdot \prod_{i=1}^j s_i = (1 + g_n)^{-j} \prod_{i=1}^j s_i = \frac{s_j \mu_j}{1 + g_n} \quad \forall j = 1, \dots, J-1$$

Let $C_{j,t}$ be aggregate consumption per age- j agent, which is derived from the age- j agent's allocation:

$$C_{j,t} = \int (1 + g_w)^t c_j(a, \varepsilon, x, \zeta) d\lambda_j = (1 + g_w)^t \int c_j(a, \varepsilon, x, \zeta) d\lambda_j = (1 + g_w)^t C_j$$

where C_j is the stationary aggregate consumption per age- j agent. Accordingly, aggregate consumption is:

$$\begin{aligned} C_t &= N_t \left(C_{1,t} + s_1(1 + g_n)^{-1} C_{2,t} + \dots + \left(\prod_{i=1}^{J-1} s_i \right) (1 + g_n)^{-(J-1)} C_{J,t} \right) \\ &= (1 + g_w)^t N_t \sum_{j=1}^J \mu_j C_j \\ &= (1 + g)^t C \end{aligned}$$

where C is the stationary level of aggregate consumption and where we have normalized $N = 1$.

We can similarly construct the remaining aggregates $\{A, K, Y, B, G\}$ on the balanced growth path. Notably, however, labor per capita does not grow. Aggregate labor per capita is constructed as:

$$L_t = N_t \sum_{j=1}^J \mu_j L_j \implies L = \frac{L_t}{N_t} = \sum_{j=1}^J \mu_j \int \zeta_j'(a, \varepsilon, x, \zeta) \varepsilon h_j(a, \varepsilon, x, \zeta) d\lambda_j$$

which is the sum over ages of aggregate labor per age- j agent.

A.1.4 Infinitely Lived Agent Model

In order to isolate the effects on optimal policy due to fundamental differences in the life cycle and infinitely lived agent models, and not due to differences in balanced growth path constructs, we want sources of output growth (e.g. TFP and population growth) to be consistent across models. Thus, we incorporate population growth into the infinitely lived agent model. To be consistent with the life cycle model, we construct a balanced growth path in which the infinitely lived agent model's income and wealth distributions grow homothetically. Our representation of this growth concept is consistent with a dynastic model in which population growth arises from agents producing offspring and valuing the utility of their offspring.

To elaborate in more detail, two additional assumptions admit a balanced growth path with population growth. First, agents exogenously reproduce at rate g_n and next period's offspring are identical to each other. Second, the parent values each offspring identically, and furthermore values each offspring as much as they value their self. Formally, if the parent has continuation value $\beta \mathbb{E}[v(a', \varepsilon')]$, then the parent values all its offspring with total value of $g_n \beta \mathbb{E}[v(a', \varepsilon')]$.

These two assumptions imply two features. First, each offspring is identical to its parent. That is, if the parent's state vector is (a', ε') next period, then so is each offspring's state vector. As a result, the value function of each offspring upon birth is $v(a', \varepsilon')$. Second, since the parent values each offspring equal to its own continuation value, it is optimal for the parent to save $(1 + g_n)a'$ in total. The portion $g_n a'$ is bequeathed to offspring, and the portion a' is kept for next period.

Individual Problem: On the balanced growth path of the Infinitely Lived Agent Model, the stationary dynamic program is then:

$$v(a, \varepsilon) = \max_{c, a', h} U(c, h) + [\beta(1 + g_w)^{1-\sigma}](1 + g_n) \sum_{\varepsilon'} \pi(\varepsilon' | \varepsilon) v(a', \varepsilon')$$

s.t.

$$c + (1 + g_n)(1 + g_w)a' \leq w\epsilon h + (1 + r)a - T(y)$$

where $y \equiv w\epsilon h + ra$ and optimality conditions are given by:

$$\begin{aligned}\chi v(h) &= u'(c)w\epsilon(1 - T'(y)) \\ u'(c) &= \beta(1 + g_w)^{-\sigma}(1 + r) \sum_{\epsilon'} \pi(\epsilon'|\epsilon)u'(c')(1 - T'(y')).\end{aligned}$$

Notice that the optimality conditions do not change relative to a world without population growth. However, the cost of savings has increased since agents bequeath wealth to offspring.

Distribution: The distribution evolves according to:

$$\lambda_{t+1}(a_{t+1}, \epsilon_{t+1}) = \sum_{\epsilon_t} \pi(\epsilon_{t+1}|\epsilon_t) \int_A \mathbb{1}[a'_{t+1}(a_t, \epsilon_t) = a_{t+1}] \lambda_t(a_t, \epsilon_t) da_t$$

The stationary distribution $\lambda(a, \epsilon)$ has measure 1 over $\mathcal{A} \times \mathcal{E}$ but the mass of agents grows at rate g_n :

$$\begin{aligned}\lambda_t(a_t, \epsilon) &= \lambda_{t-1}\left(\frac{a_t}{1 + g_w}, \epsilon\right) (1 + g_n) \\ &= \lambda_{t-s}\left(\frac{a_t}{(1 + g_w)^s}, \epsilon\right) (1 + g_n)^s \quad \forall s \leq t \\ &= \lambda(a, \epsilon) N_t\end{aligned}$$

Therefore, applying the transformation above and normalizing by N_{t+1} yields:

$$\lambda(a', \epsilon') = \sum_{\epsilon} \pi(\epsilon'|\epsilon) \int_A \mathbb{1}[a'(a, \epsilon) = a'] \frac{\lambda(a, \epsilon)}{1 + g_n} da$$

Aggregation: To construct aggregate consumption, wealth, savings and labor, multiply individual allocations by the size of the population (N_t) and sum using the stationary distribution λ . For example, aggregate consumption is:

$$C_t = N_t \int (1 + g_w)^t c(a, \epsilon) d\lambda = (1 + g)^t \int c(a, \epsilon) d\lambda = (1 + g)^t C$$

We can similarly construct the remaining aggregates $\{A, K, Y, B, G\}$ on the balanced growth path. Notably, however, aggregate labor per capita does not grow:

$$\frac{L_t}{N_t} = \int \varepsilon h(a, \varepsilon) d\lambda$$

where again $N_0 = 1$ by normalization.

A.2 Welfare Decomposition

Proposition 1: *If preferences are additively separable in utility over consumption, $u(c)$, and disutility over hours, $v(h)$, then welfare changes can be decomposed as:*

$$(1 + \Delta_{CEV}) = \underbrace{[(1 + \Delta_{C_l})(1 + \Delta_{H_l})]}_{\equiv (1 + \Delta_l)} \cdot \underbrace{[(1 + \Delta_{C_d})(1 + \Delta_{H_d})]}_{\equiv (1 + \Delta_d)}.$$

Proof: Consider two economies, $i \in \{1, 2\}$. Define ex ante welfare in economy

$i \in \{1, 2\}$ as:

$$S^i = S_c^i + S_h^i \equiv \int \mathbb{E}_0 \left[\sum_{j=1}^J \beta^{j-1} s_j u(c_j^i) \right] d\lambda_1^i + \int \mathbb{E}_0 \left[\sum_{j=1}^J \beta^{j-1} s_j \zeta_j^i v(h_j^i) \right] d\lambda_1^i.$$

Denote the Consumption Equivalent Variation (CEV) by Δ_{CEV} , which is defined as the percent of expected lifetime consumption that an agent inhabiting economy $i = 1$ would pay *ex ante* in order to inhabit economy $i = 2$:

$$(1 + \Delta_{CEV})^{1-\sigma} S_c^1 + S_h^1 = S^2.$$

Furthermore, define an individual's certainty equivalent consumption as the level $\bar{c}(a, \varepsilon, x, \zeta)$ such that the individual is indifferent between consuming $\bar{c}(a, \varepsilon, x, \zeta)$ at every age with certainty and consuming according to policy

function $\{c_j(a, \varepsilon, x, \zeta)\}_{j=1}^J$ with uncertainty. That is, $\bar{c}(a, \varepsilon, x, \zeta)$ is defined by:

$$S_c^i \equiv \int \mathbb{E}_0 \left[\sum_{j=1}^J \beta^{j-1} s_j u(c_j^i) \right] d\lambda_1^i = \left(\sum_{j=1}^J \beta^{j-1} s_j \right) \int u(\bar{c}^i(a_1, \varepsilon_1, x_1, \zeta_1)) d\lambda_1^i$$

which implies the definition of aggregate certainty equivalent consumption:

$$\bar{C}^i \equiv \int \bar{c}_1^i(a_1, \varepsilon_1, x_1, \zeta_1) d\lambda_1^i$$

Therefore, if agents only consume their certainty equivalent consumption allocation, then they only face ex ante risk in their consumption. Following [Flooden \(2001\)](#), define the *redistribution effect* by a comparison between consuming an individual and aggregate certainty equivalent consumption allocation:

$$\int \mathbb{E}_0 \left[\sum_{j=1}^J \beta^{j-1} s_j u((1 - \omega_R^i) \bar{C}^i) \right] d\lambda_1^i = \left(\sum_{j=1}^J \beta^{j-1} s_j \right) \int u(\bar{c}^i(a_1, \varepsilon_1, x_1, \zeta_1)) d\lambda_1^i$$

which implies:

$$1 - \omega_R^i = \frac{(S_c^i / \sum_{j=1}^J \beta^{j-1} s_j)^{\frac{1}{1-\sigma}}}{\bar{C}^i} \quad \text{and} \quad 1 + \Delta_{C_R} \equiv \frac{1 - \omega_R^2}{1 - \omega_R^1} = \frac{(S_c^2 / S_c^1)^{\frac{1}{1-\sigma}}}{\bar{C}^2 / \bar{C}^1}.$$

Likewise, define the *uncertainty effect* as a comparison between consuming at each age, the aggregate consumption allocation:

$$C^i = \sum_{j=1}^J \mu_j \int c_j^i(a, \varepsilon, x, \zeta) d\lambda_j^i$$

and the aggregate certainty equivalent consumption, \bar{C}^i . Then:

$$\int \mathbb{E}_0 \left[\sum_{j=1}^J \beta^{j-1} s_j u((1 - \omega_I^i) C^i) \right] d\lambda_1^i = \left(\sum_{j=1}^J \beta^{j-1} s_j \right) \int u(\bar{C}^i) d\lambda_1^i$$

which implies:

$$1 - \omega_I^i = \frac{\bar{C}^i}{C^i} \quad \text{and} \quad 1 + \Delta_{C_I} = \frac{1 - \omega_I^2}{1 - \omega_I^1}$$

Lastly, define the labor disutility effect Δ_H as the percent of lifetime consumption that an individual would pay to change their hours allocation:

$$(1 + \Delta_H)^{1-\sigma} S_c^2 = S_c^2 + (S_h^2 - S_h^1)$$

Proceeding from the definition of the CEV, we can decompose welfare as follows:

$$\begin{aligned} (1 + \Delta_{CEV}) &= (1 + \Delta_{C_l}) \cdot (1 + \Delta_{C_l}) \cdot (1 + \Delta_{C_R}) \cdot (1 + \Delta_H) \\ \left(\frac{S^2 - S_h^1}{S_c^1} \right)^{\frac{1}{1-\sigma}} &= (C^2/C^1) \cdot \frac{\bar{C}^2/\bar{C}^1}{C^2/C^1} \cdot \frac{(S_c^2/S_c^1)^{\frac{1}{1-\sigma}}}{\bar{C}^2/\bar{C}^1} \cdot \frac{((S^2 - S_h^1)/S_c^1)^{\frac{1}{1-\sigma}}}{(S_c^2/S_c^1)^{\frac{1}{1-\sigma}}} \end{aligned}$$

Canceling terms on the right hand side of the expression readily shows a decomposition holds as desired. In the text, we combine $(1 + \Delta_{C_l})(1 + \Delta_{C_R})$ as an amalgam term, $(1 + \Delta_{C_d})$, consistent with [Conesa et al. \(2009\)](#), to form the consumption distribution effect.

Decomposing the labor disutility effect into level and distribution effects follows similar reasoning. Define the hours level effect $(1 + \Delta_{H_l})$ as the labor disutility that an agent would be willing to accept in order to work H^2 hours each period instead of H^1 hours, which implies that $(1 + \Delta_{H_l}) = H^2/H^1$. Finally, define the hours distribution effect as the residual of the labor disutility effect after accounting for the hours level effect:

$$(1 + \Delta_{H_d}) = \frac{((S^2 - S_h^1)/S_c^2)^{\frac{1}{1-\sigma}}}{H^2/H^1}.$$

Therefore the decomposition gives $(1 + \Delta_H) = (1 + \Delta_{H_l})(1 + \Delta_{H_d})$. ■